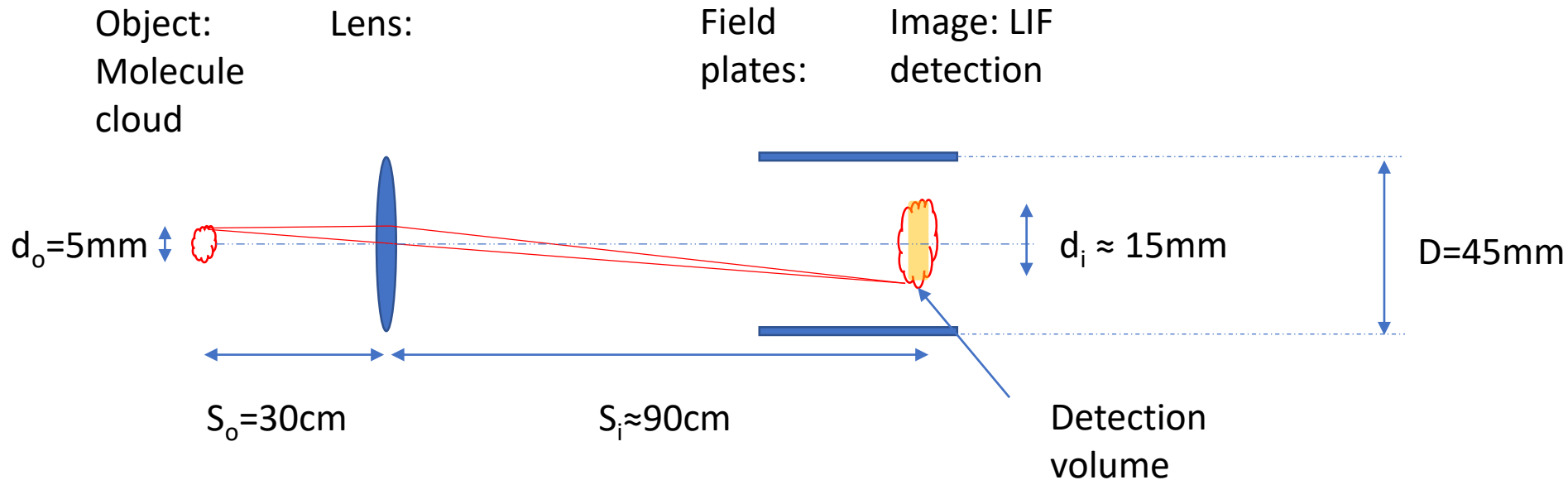


Towards eliminating ThO trajectories which hit the ITO coated Field Plates

Xing Wu

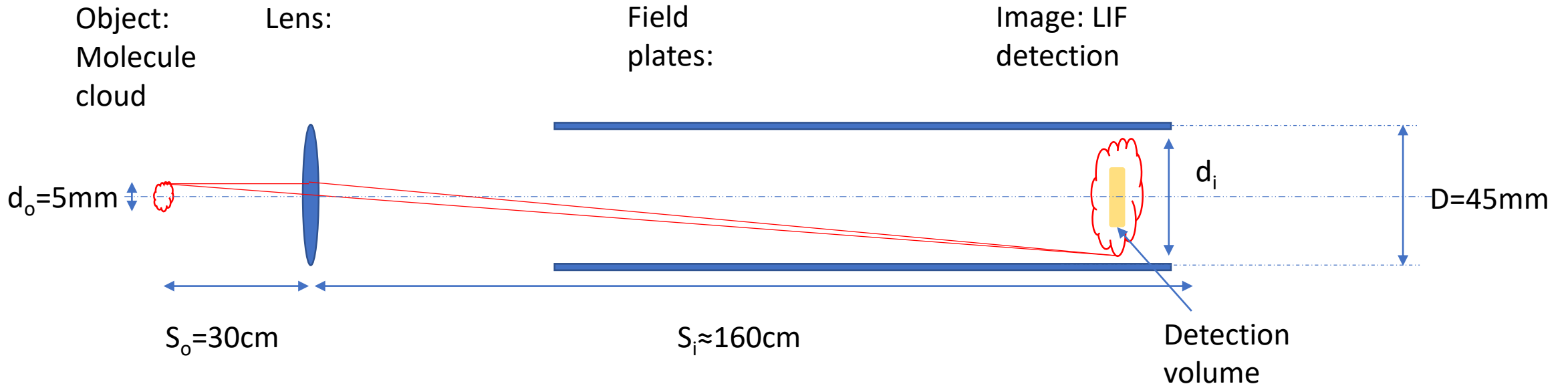
To avoid hitting the extended field plates

- '0th order' approximation:
 - Using ideal lens formula, and object has finite size (no aberration, no fuzziness)
 - Magnification= $d_i/d_o=S_i/S_o$



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- Longer field plates \rightarrow larger image. If take aberration (i.e. 'fuzziness' of the image) into account:
 - \rightarrow smaller signal for a given finite detection volume (we already knew)
 - \rightarrow more likely to hit the field plates

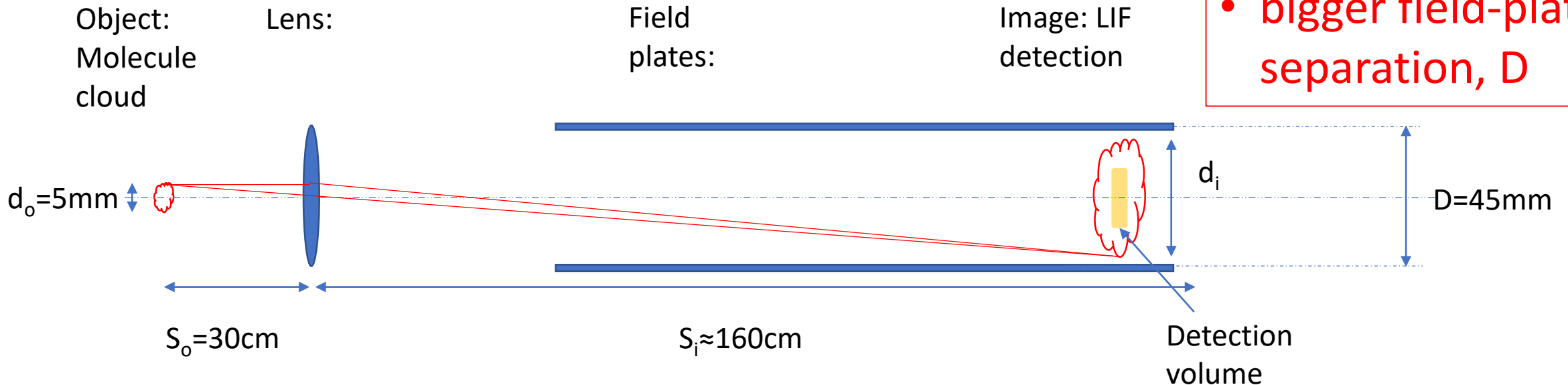


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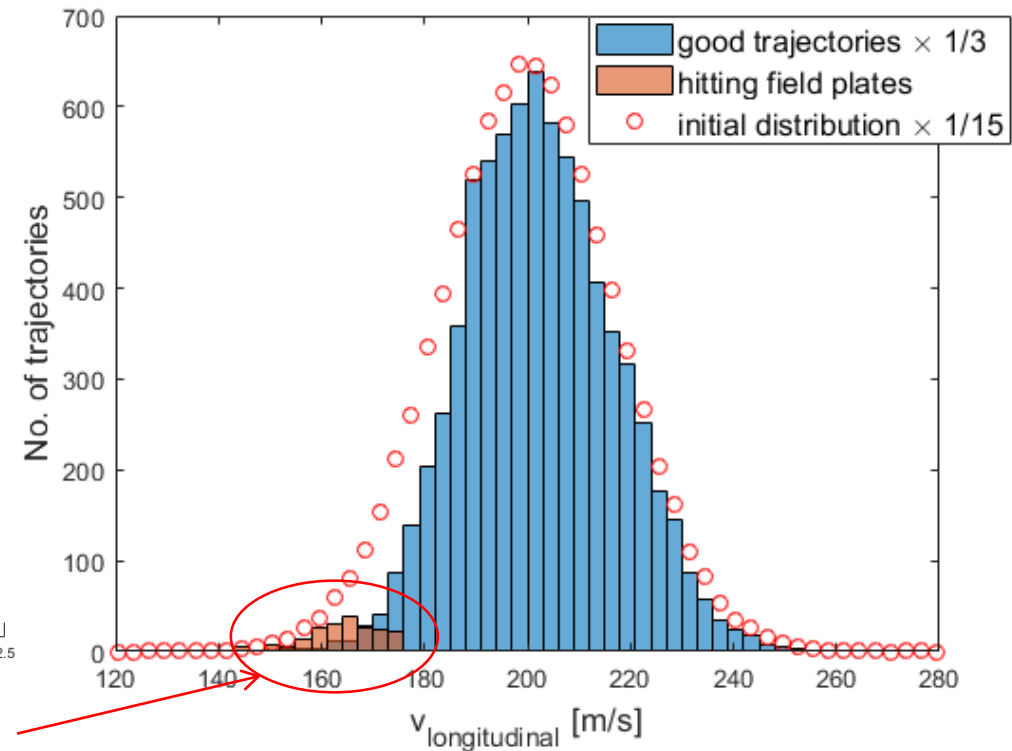
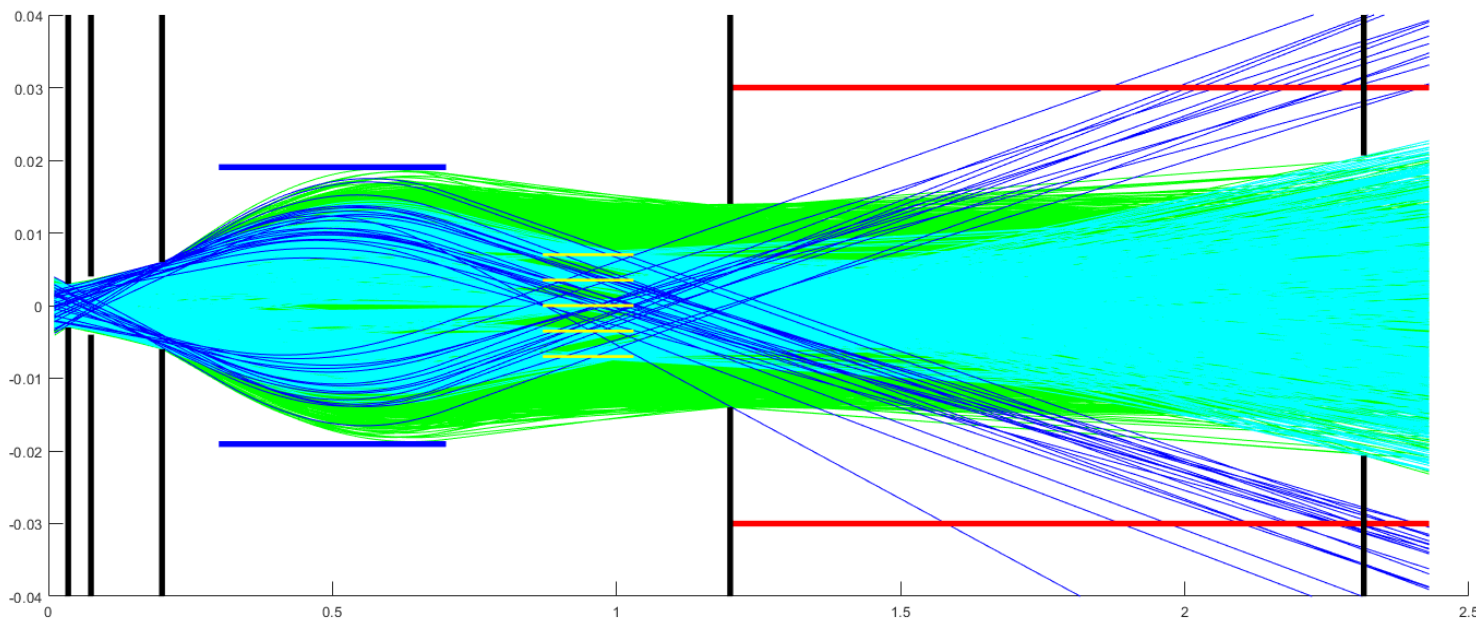
'Desirable' feature:

- Lens-to-field-plates distance as short as possible
- bigger field-plates separation, D



Looking at the trajectories

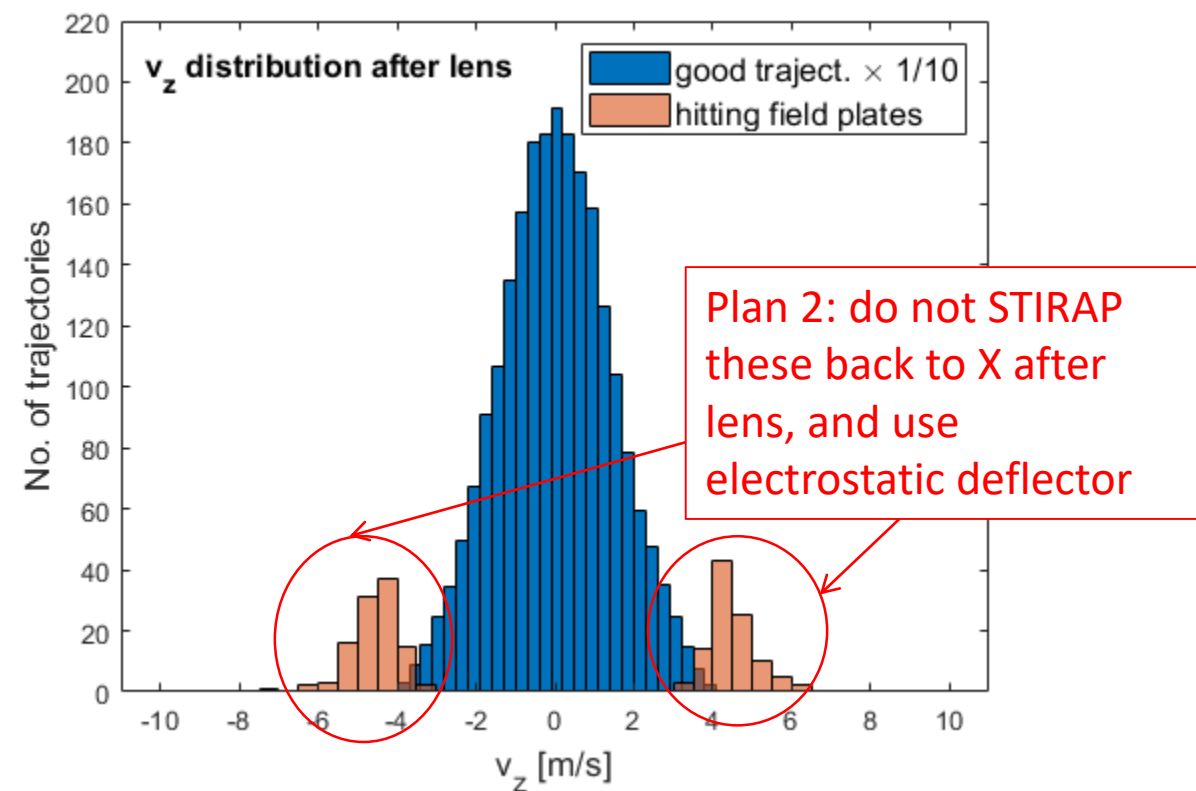
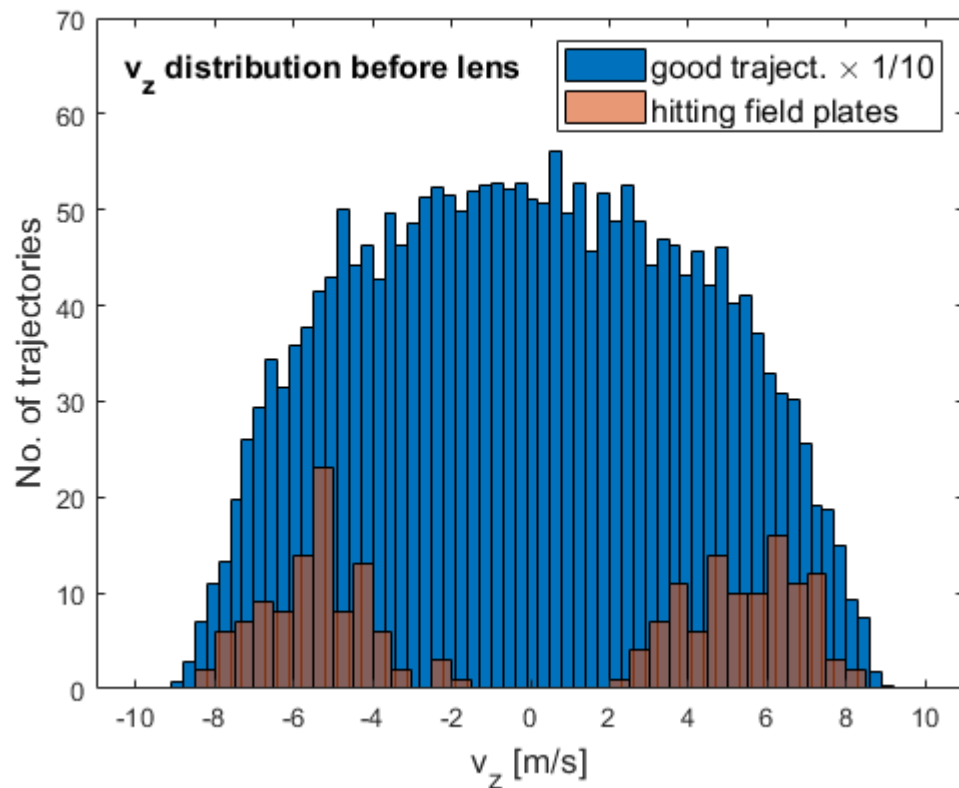
- Major difference between good & bad: longitudinal velocities



Plan 1: pump them out of the X-C-Q STIRAP ground state after rotational cooling & before STIRAP takes place

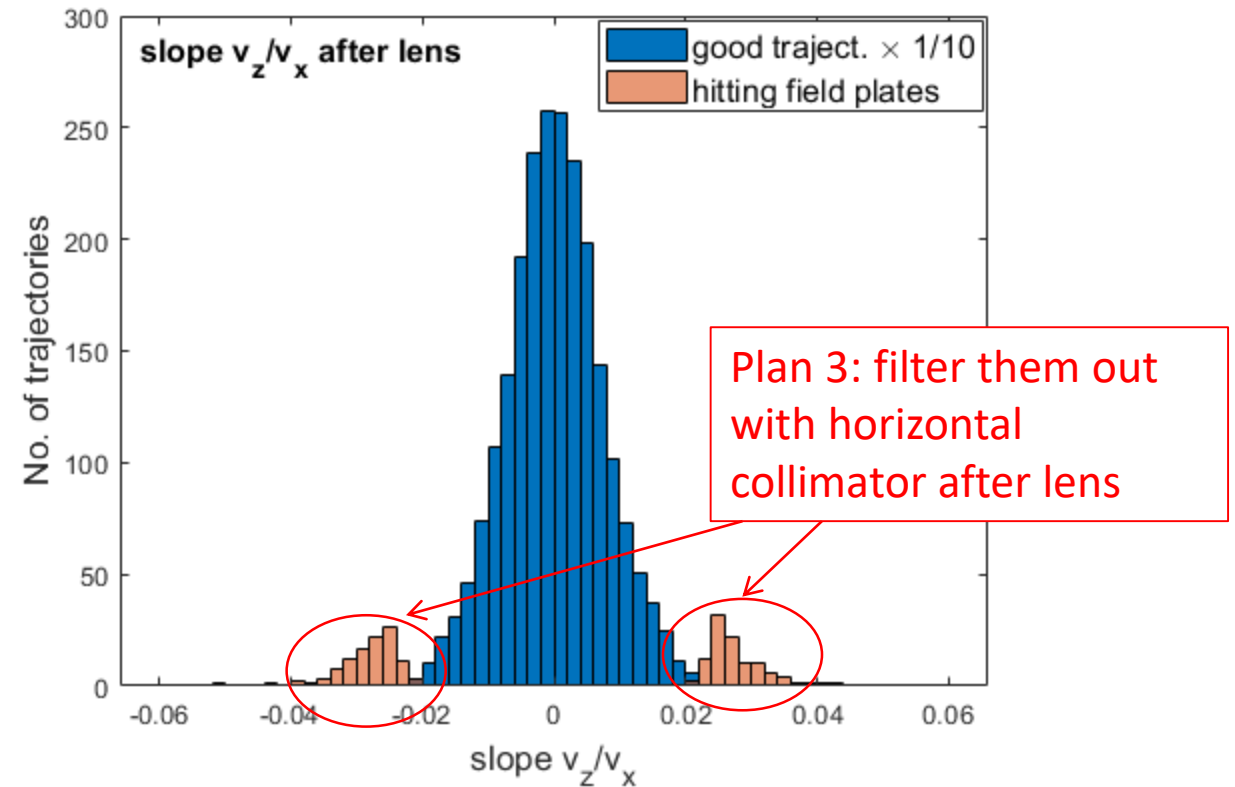
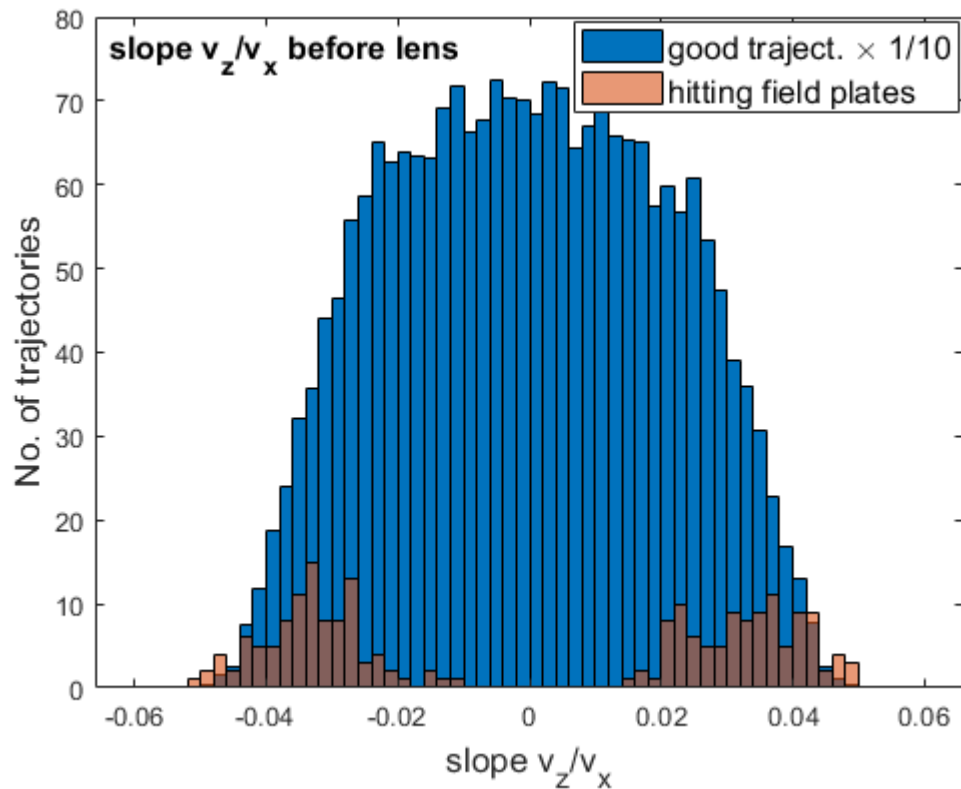
Transverse velocity (v_z) (z is the same as defined in ACME II)

- Cannot differentiate good & bad trajectories in v_z before lens. But they get separated after lens because the bad ones are all slower in v_x and hence spend longer time in lens \rightarrow over-focused



Trajectory slope (v_z/v_x)

- The differentiation gets 'doubly' enhanced by looking at the slope (v_z/v_x). This is what the horizontal collimator tries to filter out. However, because of convolution between spatial distribution and slope of the trajectories, about x20 times more good trajectories (about 17% of all the good trajectories) are blocked than the bad ones (100% of the bad ones). Scatter from the collimator surfaces are not included yet



Proposed sensitivity gain for ACME III

extending Field Plates: from 43cm (2x11.5cm for fringing Fields + 20cm for spin precession) to 123cm

Also need to avoid 'direct' coating of ThO on Field Plates

$$\delta d_e = \frac{1}{2T \mathcal{E}_{eff} \sqrt{N}}$$

Improvement	Signal Gain	EDM Sensitivity Gain
Increased Precession Time	0.20	2.3
Electrostatic Lens	16	4
SiPM Detector Upgrade	2.3	1.5
Timing Jitter Noise Reduction	1	1.7
Total	7.4	23.5